

Part-turn actuator			Motor									
Type	Operating time for 90° in seconds	Max. torque [Nm]	Motor type	Nominal power ¹⁾ P _N [kW]	Speed [rpm]	Nominal current ²⁾ I _N (A)	Max. current ³⁾ I _{max} [A]	Starting current I _A [A]	cos φ	Overcurrent protection device setting [A]	AUMA power class for switch-gear	
											Contactor	Thyristor
SQ 05.2	4	150	VD00063-2-0,06	0.06	2,800	0.6	0.6	1.9	0.42	0.6	A1	B1
	5.6					0.6	0.6	1.9	0.42	0.6	A1	B1
	8		VD00063-4-0,04	0.04	1,400	0.4	0.4	1.0	0.50	0.4	A1	B1
	11					0.4	0.4	1.0	0.50	0.4	A1	B1
	16		VD00063-4-0,02	0.02	1,400	0.4	0.4	1.0	0.40	0.4	A1	B1
	22					0.4	0.4	1.0	0.40	0.4	A1	B1
	32		SD00063-4-0,01	0.01	1,400	0.3	0.3	0.7	0.38	0.3	A1	B1
	63		SD00063-8-0,01	0.01	700	0.4	0.4	0.5	0.61	0.4	A1	B1
SQ 07.2	4	300	VD00063-2-0,12	0.12	2,800	0.7	0.9	3.0	0.52	0.9	A1	B1
	5.6					0.7	0.9	3.0	0.52	0.9	A1	B1
	8		VD00063-4-0,06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	11					0.6	0.7	1.6	0.38	0.7	A1	B1
	16		VD00063-4-0,03	0.03	1,400	0.4	0.5	1.0	0.43	0.5	A1	B1
	22					0.4	0.5	1.0	0.43	0.5	A1	B1
	32		SD00063-4-0,01	0.01	1,400	0.3	0.3	0.7	0.38	0.3	A1	B1
	63		SD00063-8-0,01	0.01	700	0.4	0.4	0.5	0.61	0.4	A1	B1
SQ 10.2	8	450	VD00063-4-0,10	0.10	1,400	0.8	1.0	2.0	0.48	1.0	A1	B1
	11					0.8	0.9	2.0	0.48	0.9	A1	B1
	16		SD00063-4-0,06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	22					0.6	0.7	1.6	0.38	0.7	A1	B1
	32		SD00063-4-0,04	0.04	1,400	0.5	0.5	1.0	0.48	0.5	A1	B1
	45					0.5	0.5	1.0	0.48	0.5	A1	B1
	63		SD00063-4-0,02	0.02	1,400	0.3	0.3	0.7	0.43	0.3	A1	B1
SQ 12.2	11	900	VD00063-2-0,19	0.19	2,800	1.0	1.2	3.5	0.53	1.2	A1	B1
	16					0.8	1.0	2.0	0.48	1.0	A1	B1
	22		VD00063-4-0,10	0.10	1,400	0.8	0.9	2.0	0.48	0.9	A1	B1
	32					0.6	0.7	1.6	0.38	0.7	A1	B1
	45		SD00063-4-0,06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1
	63					0.5	0.5	1.0	0.48	0.5	A1	B1
	90		SD00063-4-0,04	0.04	1,400	0.5	0.5	1.0	0.48	0.5	A1	B1
SQ 14.2	125	1,200				0.3	0.3	0.7	0.43	0.3	A1	B1
	24		VD00063-2-0,19	0.19	2,800	1.0	1.2	3.5	0.53	1.2	A1	B1
	36					0.8	0.9	2.0	0.48	0.9	A1	B1
	48		VD00063-4-0,10	0.10	1,400	0.8	0.9	2.0	0.48	0.9	A1	B1
	72					0.6	0.7	1.6	0.38	0.7	A1	B1
	100		SD00063-4-0,06	0.06	1,400	0.6	0.7	1.6	0.38	0.7	A1	B1

1) – 3) Refer to Notes on Electrical data SQ .2/SQR .2 part-turn actuators with 3-phase AC motors

We reserve the right to alter data according to improvements made. Previous documents become invalid with the issue of this document.

Installation and sizing

Motor data	Motor data is approximate. Due to usual manufacturing tolerances, there may be deviations from the values given.																			
Motor protection	To protect against overheating, thermoswitches or PTC thermistors are embedded in the motor windings.																			
Actuators without integral actuator controls (AUMA NORM):																				
Thermoswitches or PTC thermistors have to be considered within the external controls (refer to terminal plan).																				
Note: Failure to connect thermoswitches or PTC thermistors shall void the warranty for the motor.																				
Rating of the thermoswitches																				
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Actuators with AM or AC integral actuator controls:																				
Thermal motor protection is already integrated.																				
Mains voltage, mains frequency	Permissible variation of mains voltage: $\pm 10\%$ Permissible variation of mains frequency: $\pm 5\%$																			
Switchgear sizing	For motor operation, reversing contactors (mechanically, electrically and electronically locked) or thyristors (electronically locked) can be used.																			
Actuators without integral actuator controls (AUMA NORM):																				
Switchgear are supplied by the customer. We recommend specification of switchgear suitable for their rated operating power/motor power in compliance with the assigned AUMA power class.																				
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Required switchgear in power classes A1 or B1 are directly integrated in AM or AC actuator controls.																				

Notes on Electrical data SQ .2/SQR .2 part-turn actuators with 3-phase AC motors

1) Nominal power P_N	Mechanical power output at motor shaft at run torque of part-turn actuator (corresponds to approx. 35 % of maximum torque).
2) Nominal current I_N	Current at run torque
3) Max. current I_{max}	Current at maximum torque